

CLAIM AMENDMENTS

1. (CURRENTLY AMENDED) A method for electronic tuning of the frequency of a ~~the~~ read oscillation to the frequency of a ~~the~~ stimulation oscillation in a Coriolis gyro wherein

- a ~~the~~ resonator of the Coriolis gyro has a disturbance force applied to the resonator ~~it~~ such that

a) the stimulation oscillation remains essentially uninfluenced, and

b) the read oscillation is changed such that a signal which represents the read oscillation contains a corresponding disturbance component, wherein

- the frequency of the read oscillation is controlled such that any phase shift between a disturbance signal which produces the disturbance force and the disturbance component which is contained in the read signal is as small as possible.

2. (CURRENTLY AMENDED) The method as claimed in claim 1, characterized in that a ~~the~~ disturbance force is produced by a disturbance signal which is added to the respective control/reset signals for control/compensation of the read oscillation.

3. (PREVIOUSLY PRESENTED) The method as claimed in claim 1, characterized in that the disturbance signal is an alternating signal.

4. (ORIGINAL) The method as claimed in claim 3, characterized in that the disturbance signal is at a fixed disturbance frequency, and the disturbance component is determined from the read signal by demodulation of the read signal at the fixed disturbance frequency.

5. (PREVIOUSLY PRESENTED) The method as claimed in claim 1, characterized in that the disturbance signal is a band-limited noise signal.

6. (ORIGINAL) The method as claimed in claim 5, characterized in that the disturbance component is demodulated from the read signal by correlation of the disturbance signal with the read signal.

7. (CURRENTLY AMENDED) The method as claimed in claim 2, characterized in that the disturbance signal is added to an ~~the~~ output signal from a ~~the~~ quadrature control loop, and the disturbance component is determined from a signal which is applied to a quadrature regulator in the ~~athe~~ quadrature control loop, or is emitted from the quadrature regulator ~~it~~.

8. (CURRENTLY AMENDED) The method as claimed in claim 2, characterized in that the disturbance signal is added to an ~~the~~ output signal from a ~~the~~ rotation rate control loop, and the disturbance component is determined from a signal which is applied to a rotation rate regulator in the rotation rate control loop, or is emitted from the rotation rate regulator ~~it~~.

9. (PREVIOUSLY PRESENTED) The method as claimed in claim 2, characterized in that the frequency of the read oscillation is controlled by controlling the intensity of an electrical field in which a part of the resonator of the Coriolis gyro oscillates.

10. (CURRENTLY AMENDED) A Coriolis gyro which has a rotation rate control loop and a quadrature control loop, characterized by a device for electronic tuning of the frequency of a ~~the~~ read oscillation to the frequency of a ~~the~~ stimulation oscillation, having:

- a disturbance unit which passes a disturbance signal to the rotation rate control loop or to the quadrature control loop,
- a disturbance signal detection unit, which determines a disturbance component which is contained in a read signal, ~~(which~~ represents the read oscillation~~,)~~ and has been produced by the disturbance signal, and
- a control unit, which controls the frequency of the read oscillation such that any phase shift between the disturbance signal and the disturbance component which is contained in the read signal is as small as possible.

11. (CURRENTLY AMENDED) The Coriolis gyro as claimed in claim 10, characterized in that the disturbance unit passes the disturbance signal to the rotation rate control loop, and the disturbance signal detection unit determines the disturbance component from a signal which is applied to a rotation rate regulator in the rotation rate control loop, or is emitted from the rotation rate regulator ~~it~~.

12. (CURRENTLY AMENDED) The Coriolis gyro as claimed in claim 10, characterized in that the disturbance unit passes the disturbance signal to the quadrature control loop, and the disturbance signal detection unit determines the disturbance component from a signal which is applied to a quadrature regulator in the quadrature control loop, or is emitted from it.